# 18.100A PROBLEM SET 7 

due May 10th 9:30 am

You can collaborate with other students when working on problems. However, you should write the solutions using your own words and thought.

Problem 1. Exercise 22.1.1. Page 32.
Problem 2. Exercise 22.2.2. Page 322.
Problem 3. Exercise 22.2.4. Page 323.
Problem 4. Exercise 22.3.3. Page 323.
Problem 5. Exercise 22.6.5.(a) Page 324. (Hint: Integration.)
Definition (Stereographic projection)
We define a map $P: \mathbb{R}^{2} \rightarrow \mathbb{R}^{3}$ by

$$
P(x, y)=\left(\frac{2 x}{1+x^{2}+y^{2}}, \frac{2 y}{1+x^{2}+y^{2}}, \frac{-1+x^{2}+y^{2}}{1+x^{2}+y^{2}}\right) .
$$

Then, the image $P\left(\mathbb{R}^{2}\right)$ is $S^{2} \backslash\{(0,0,1)\}$ where $S^{2}$ is the unit sphere $\left\{\left(v_{1}, v_{2}, v_{3}\right) \in\right.$ $\left.\mathbb{R}^{3}: v_{1}^{2}+v_{2}^{2}+v_{3}^{2}=1\right\}$. Moreover, $P$ is one-to-one.

Namely, $P$ is mapping a plane to a sphere. So, if Kyeongsu considers the earth flat while Archimedes considers the earth round, the map $P$ provides the relation between points of the earth in their own minds.

Problem 6 (20 points). We define a function $d: \mathbb{R}^{2} \times \mathbb{R}^{2} \rightarrow \mathbb{R}$ by

$$
d\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right)=\sqrt{1-P\left(x_{1}, y_{1}\right) \cdot P\left(x_{2}, y_{2}\right)}
$$

where $P\left(x_{1}, y_{1}\right) \cdot P\left(x_{2}, y_{2}\right)$ implies the dot product of the three dimensional unit vectors $P\left(x_{1}, y_{1}\right), P\left(x_{2}, y_{2}\right)$.

Show that the following hold
(1) $d \geq 0$, and $d\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right)=0$ if and only if $\left(x_{1}, y_{1}\right)=\left(x_{2}, y_{2}\right)$.
(2) $d\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right)=d\left(\left(x_{2}, y_{2}\right),\left(x_{1}, y_{1}\right)\right)$.
(3) $d\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right)+d\left(\left(x_{2}, y_{2}\right),\left(x_{3}, y_{3}\right)\right) \geq d\left(\left(x_{1}, y_{1}\right),\left(x_{3}, y_{3}\right)\right)$.

Namely, $d$ is a distance of $\mathbb{R}^{2}$. You can use the facts given in the blue lines.
Remark. We define a function $\theta: \mathbb{R}^{2} \times \mathbb{R}^{2} \rightarrow \mathbb{R}$ by

$$
\theta\left(\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right)=\arccos \left|P\left(x_{1}, y_{1}\right) \cdot P\left(x_{2}, y_{2}\right)\right| .
$$

Namely, $\theta$ is the angle between the two unit vectors $P\left(x_{1}, y_{1}\right), P\left(x_{2}, y_{2}\right)$. Then, $\theta$ implies the length of the shortest curve on the unit sphere, which connects the two points $P\left(x_{1}, y_{1}\right), P\left(x_{2}, y_{2}\right)$.

One can prove that the angle function $\theta$ is a distance by using the Pythagoras theorem and elementary geometry as like ancient Greek mathematicians.

## Welcome to Geometry!

